



VP160 RECITATION CLASS

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Kinematics in 3D: Cartesian Coordinates

Kinematics in 3D: Cylindrical and Spherical Coordinates

Kinematics in 3D: Natural Coordinates

Kinematics in 2D: polar coordinates

Kinematics in 3D: Cartesian Coordinates

Basic Formulas

$$\vec{r} = x(t)\hat{n}_x + y(t)\hat{n}_y + z(t)\hat{n}_z$$

$$\vec{v} = \dot{x}(t)\hat{n}_x + \dot{y}(t)\hat{n}_y + \dot{z}(t)\hat{n}_z$$

$$\vec{a} = \ddot{x}(t)\hat{n}_x + \ddot{y}(t)\hat{n}_y + \ddot{z}(t)\hat{n}_z$$

Kinematics in 3D: Cylindrical and Spherical Coordinates

Basic Formulas

$$\vec{r} = \rho \hat{n}_\rho + z \hat{n}_z$$

$$\vec{v} = \dot{\rho} \hat{n}_\rho + \rho \dot{\phi} \hat{n}_\phi + \dot{z} \hat{n}_z$$

$$\vec{a} = (\ddot{\rho} - \rho \dot{\phi}^2) \hat{n}_\rho + (\rho \ddot{\phi} + 2\dot{\rho} \dot{\phi}) \hat{n}_\phi + \ddot{z} \hat{n}_z$$

Remind: Do remember these formulas, otherwise you may derive them by yourselves during the exam!

Kinematics in 3D: Natural Coordinates

Basic Vectors

1. \hat{n}_τ : along the direction of \vec{v}
2. \hat{n}_n and \hat{n}_b : perpendicular to the direction of \vec{v}

Kinematics in 3D: Natural Coordinates

Basic Vectors

1. \hat{n}_τ : along the direction of \vec{v}
2. \hat{n}_n and \hat{n}_b : perpendicular to the direction of \vec{v}

Basic Formulas

$$\hat{n}_\tau = \frac{\vec{v}}{\|\vec{v}\|}$$

$$\hat{n}_n = \frac{d\hat{n}_\tau/dt}{\|d\hat{n}_\tau/dt\|}$$

$$\hat{n}_b = \hat{n}_\tau \times \hat{n}_n$$

$$\vec{v} = v\hat{n}_\tau$$

$$\vec{a} = \dot{v}\hat{n}_\tau + \frac{v^2}{R_c}\hat{n}_n$$

Important Tips

1. Differences between $\dot{\vec{v}}$ and \dot{v} .
2. Differences between **radial/transversal**, **normal/tangential**.

Kinematics in 2D: Polar Coordinates

Basic Formulas

$$d\vec{r} = d\rho\hat{n}_\rho + \rho d\phi\hat{n}_\phi$$
$$(ds)^2 = (d\rho)^2 + (\rho d\phi)^2$$

Exercise 1

A particle moves in the x - y plane so that

$$x(t) = at, y(t) = bt^2$$

where a , b are positive constants. Find its trajectory, velocity, and acceleration (its tangential and normal components).



Exercise2

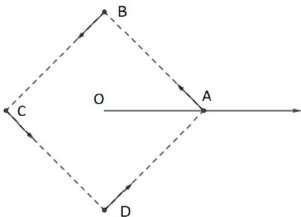
A disc of radius R rotates about its axis of symmetry (perpendicular to the disk surface) with constant angular velocity $\dot{\phi} = \omega = \text{const}$. At the instant of time $t = 0$ a beetle starts to walk with constant speed v_0 along a radius of the disk, from its center to the edge. Find:

- (a) the position of the beetle and its trajectory in the Cartesian and polar coordinate systems
- (b) its velocity in both systems,
- (c) its acceleration in both systems,
- (d) the distance covered by the beetle and the curvature of the trajectory.

Exercise 3

Four spiders are initially placed at the four corners of a square with side length a . The spiders crawl counter-clockwise at the same speed v and each spider crawls directly toward the next spider at all times. They approach the center of the square along spiral paths. Find:

- polar coordinates of spider A at any instant of time t
- the time after which all spiders meet
- the trajectory of a spider in polar coordinates



Exercise 4

A particle moves along a hyperbolic spiral (i.e. a curve $r = c/\phi$, where c is a positive constant), so that $\phi(t) = \phi_0 + \omega t$; where ϕ_0 and ω are positive constants. Find its velocity and acceleration (all components and magnitudes of both vectors).